REBOUND 2024: XGEO NUMERICAL INTEGRATOR ANALYSIS AND MANEUVER DETECTION

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Motivation Optical detection of suboptimal objects in suboptimal regimes



15th Space Surveillance Squadron (SPSS)

- space object detection



Mt. Haleakala, AEOS telescope (3.6 m aperture)



• Space domain awareness (SDA), space situational awareness (SSA), rendezvous proximity operations (RPOs), astronomy, spectroscopy, optimal trajectory control, near-Earth and deep-

• **Overarching objective:** Utilization of highly advanced tracking optics (including DoD's largest optical telescope) for tracking and imaging deep-space (possibly uncooperative) satellites

Suboptimal Objects

• Miniaturization of satellite technology (CubeSats) has increased the difficulty of tracking and imaging objects with smaller apparent magnitudes

Suboptimal Regimes

- xGEO objects are governed by dynamics that are less predictable than LEO or GEO objects
- Detection of lunar orbiters require telescopes to point closer to the Moon, decreasing signal-to-noise ratio and shortening viable observation periods





CAPSTONE



eillance Squadron (

eness (SDA), space situation astronomy, spectro ction

point Nov. 2022

• Period of ~ 6.5 days, periselene altitude: $\sim 1,500$ km, aposelene altitude: ~70,000 km amics that are less • Operated by Advanced Space, ephermides to point available on JPL Horizons ecreasing signal-to-noise ratio and shortening viable observation periods

Motivation of suboptimal objects in su



rendezvous proximity ontrol, near-Earth and deep-

ctive: Utilization of heavy advanced tracking optics (including DoD's cope) for tracking and imaging deep-space (possibly uncooperative) satellites • 12U CubeSat traveling in a near-rectilinear halo orbit (NRHO) about the L_2 Earth-Moon libration

• Miniaturization of satellite technology (CubeSats) has • Launched 28 Jun. 2022, inserted into NRHO on 14 objects with smaller apparent magnitudes

Brute Force Pixel Stacking for Optical Detection of CAPSTONE





Brute Force Pixel Stacking for Optical Detection of CAPSTONE



Fundamental Question: Are state-of-the-art numerical integrators accurate enough to be utilized by optical detection methods in the xGEO regime when the ephemeris is unavailable? If so, what is the limit of this accuracy with respect to the length of the propagation period?



RA (°)

 $= t_3$



Numerical Integrator Analysis Comparison of integration results to CAPSTONE ephemeris

Preliminary test: 24-hr propagation period

- Begin with initial conditions of CAPSTONE at an epoch (15 Nov 2022) provided by JPL Horizons
- Propagate using ASSIST/GMAT
 - ASSIST: Standard model
 - GMAT-4BP: Earth+Moon+Sun
 - GMAT-EJ2: All planets + Earth's J_2
 - GMAT-EMJ2: GMAT-EJ2 + Moon's J_2
- Compare propagated results with ephemeris at epochs





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Model	ASSIST	GMAT-4BP	GM.
Final Position Error (km)	0.22375	0.22222	0.
Final Velocity Error (cm/s)	0.53015	0.52648	0.



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Maneuver Detection Retrospective inspection of Cartesian residuals

- CAPSTONE performs orbit maintenance maneuvers (OMMs) to maintain the NRHO
- Maneuvers (magnitude, direction, and epoch) are not explicitly stated in ephemeris repositories
- integrator analysis





• Numerical integrators only function as accurate approximations of the ephemeris during non-maneuvering periods

• Conclusion: ability to detect that a maneuver has occurred is a necessity for performing numerical

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Instantaneous shift in velocity (indicative of a maneuver)

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Maneuver Detection Inspection over longer propagation window

• **Procedure**

- 1. Determine a propagation window wherein retrospective maneuver detection will be applied
- 15 Nov 2022 01 Jan 2023 (insertion into NRHO to EOY)
- 2. Initialize numerical integration simulations every n hours throughout the entire propagation window from ICs provided by ephemeris
 - n = 12 hours, ephemeris step size = 1 hour
- 3. Propagate simulations through window
- 4. Retrospectively analyze for each simulation where

• threshold value = 5 cm/s (per Advanced Space, maneuvers have magnitudes from 5 to 50 cm/s)

Considerations

- Large shifts in velocity between time steps are expected near periselene as velocity increases • Because of this, uncertainty of state estimation increases, thus Advanced Space has confirmed they do not
- perform OMMs "near periselene"

 $r_{LHR} =$



velocity residual error $(t + \Delta t)$ – velocity residual error(t) > threshold value

• Solution: develop "no-go" zone where maneuver triggers are ignored, Lunar Hill Region (LHR)

$$a_{\mathbb{C}} \left(\frac{m_{\mathbb{C}}}{3 \, m_{\oplus}}\right)^{1/3}$$



ConsidComplete Maneuver Detection Window - Velocity

- Large shifts in velocity between time steps are
- Because of this, "Maneuver Table estimation

Maneuver #	Maneuver Date (UTC)	# of Triggers	Trigger Rate
1	16 Nov. 2022 01:00:00	3	100%
2	18 Nov. 2022 18:00:00	5	100%
3	21 Dec. 2022 10:00:00	65	100%

expected near periselene as velocity increases

estimation increases, thus Advanced Space has confirmed they do not

- Expected ~1 maneuver/week
- Maneuver threshold value may have been too high or no-go zone may be too large
- Carry-on with assumption that 19 Nov 2022 to 21 Dec 2022 is maneuver-free period





Propagation window: 19 Nov 2022 00:00:00 UTC - 21 Dec 2022 00:00:00 UTC (32 days)





- ASSIST and GMAT-EJ2 ulletare most accurate force models
- ASSIST includes J_2 of the Sun, as well as other perturbations from asteroids that are most likely not included in the orbit determination model

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Propagation window: 19 Nov 2022 00:00:00 UTC - 21 Dec 2022 00:00:00 UTC (32 days)



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	ASSIST	GMAT-4BP	GMAT-EJ2	GMAT-EMJ2		
ror (km)	77.23441	77.99987	77.04892	159.56883		
th (km/day)	2.41358	2.43750	2.40778	4.98653		
ror (cm/s)	15.13197	15.07480	15.15035	32.59955		
th (cm/s/day)	0.47287	0.47109	0.47345	1.01874		

All code can be found at: <u>https://github.com/bhanson10/CAPSTONE</u> and <u>https://github.com/bhanson10/TESS_IBEX_Spektr-R.</u>

Thank you for your time. Questions?

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